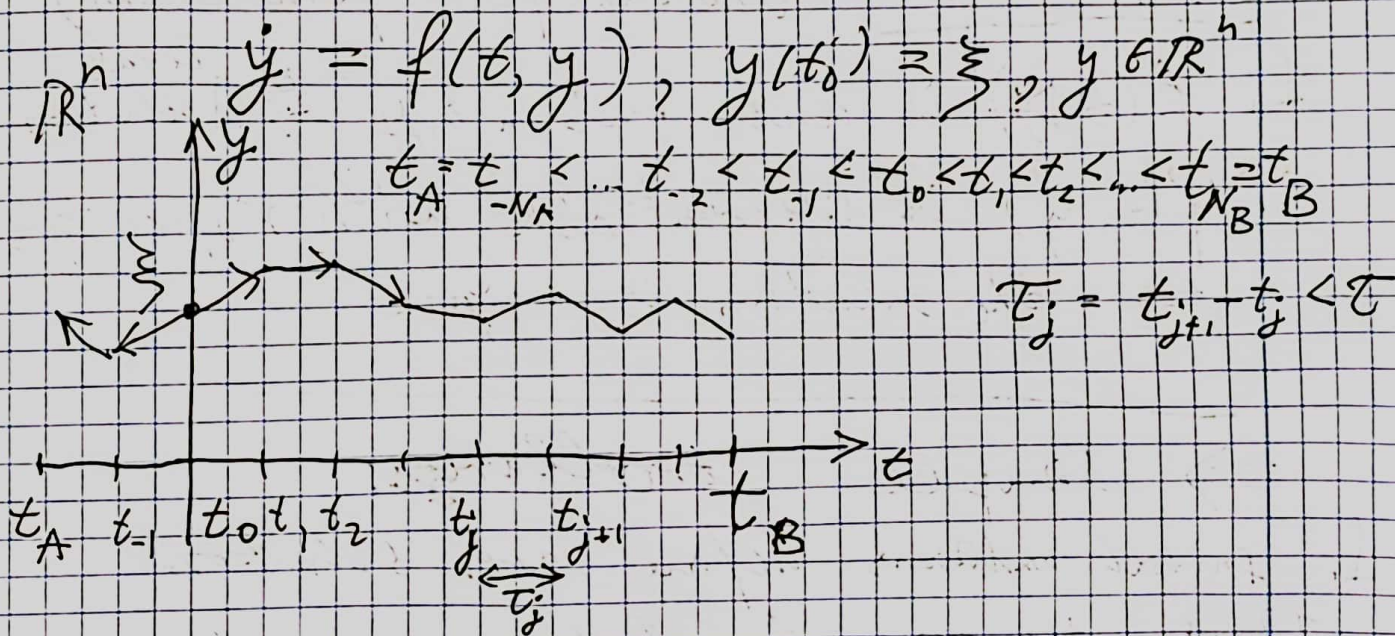


2. In all previous ^{1st order} examples and methods we actually have found Lecture 5 since they had

Theorem of existence and uniqueness of solution and each condition to be satisfied. There are singular solutions at the points where the ∃! theorem does not hold.

The theorem of ∃! is proved by approximation of solutions, which is proved to converging to them.

The Euler integration method



$$y(t_0) = \xi, y(t_1) = y(t_0) + f(t_0, y(t_0)) \tau_1, \dots$$

$$j \geq 0 \quad y(t_{j+1}) = y(t_j) + f(t_j, y(t_j)) \tau_j \quad \text{forwards}$$

$$j \leq 0 \quad y(t_j) = y(t_{j+1}) - f(t_{j+1}, y(t_{j+1})) \tau_j \quad \text{backwards}$$

$$\boxed{y(t_{**}) = y(t_*) + f(t_*, y(t_*)) (t_{**} - t_*)}$$

As $\tau \rightarrow 0$ the approximations

converge
(if it is continuous)

2

Exact formulation:

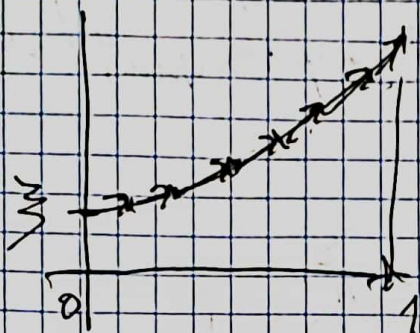
If the solution is unique, the Euler approximations converge to it uniformly on $[t_A, t_B]$

Otherwise there is a subsequence which converges uniformly to a solution.

Example

$$\dot{y} = y \in \mathbb{R}, y_0 = y(0) = \frac{1}{2}$$

$$t_A = 0, t_B = 1 \quad [0, t_B]$$



$$\text{let } \tau_j = \tau = \frac{1}{n} t_B$$

$$y_0 = \frac{1}{2}, t_0 = 0$$

$$y_1 = y_0 + \frac{t_B}{n} y_0 = \left(1 + \frac{t_B}{n}\right) \frac{1}{2}$$

$$y_2 = y_1 + \frac{t_B}{n} y_1 = \left(1 + \frac{t_B}{n}\right)^2 \frac{1}{2}$$

$$\dots$$

$$y(t_B) = y_n = y_{n-1} + \frac{t_B}{n} y_{n-1} = \left(1 + \frac{t_B}{n}\right)^n \frac{1}{2}$$

$$\lim_{n \rightarrow \infty} y_n = \lim_{n \rightarrow \infty} \left(1 + \frac{t_B}{n}\right)^n \frac{1}{2} = \frac{1}{2} e^{t_B}$$

$$q = \frac{t}{t_B} \in [0, 1] \quad \lim_{n \rightarrow \infty} y[nq] = \lim_{n \rightarrow \infty} \left(1 + \frac{t_B}{n}\right)^{[nq]} \frac{1}{2} = \lim_{n \rightarrow \infty} \left(1 + \frac{t_B}{n}\right)^{[nq]} \frac{1}{2}$$

$$0 < q < 1$$

$$[nq] \leq nq < [nq] + 1$$

$$p \leq p/n$$

$$\lim_{n \rightarrow \infty} y[nq] = \lim_{n \rightarrow \infty} \left(1 + \frac{t_B}{n}\right)^{[nq]} \frac{1}{2} =$$

$$= \lim_{n \rightarrow \infty} \left(1 + \frac{t_B q}{nq}\right)^{\frac{[nq] nq}{nq}} \frac{1}{2} =$$

$$= \lim_{n \rightarrow \infty} \left(e^1\right)^{\frac{t}{nq}} \frac{1}{2} = e^t \frac{1}{2}$$

The Euler integration can be used 3 and is used for numeric solution of ODEs

The Picard approximation method

$$\dot{y} = f(t, y), \quad y(t_0) = \xi, \quad t \in [t_A, t_B]$$

$$y(t) = y(t_0) + \int_{t_0}^t \dot{y}(s) ds = y(t_0) + \int_{t_0}^t f(s, y(s)) ds$$

The ODE is replaced with the integral one
A sequence of functional approximations is constructed now.

$$\varphi_0(t) = y(t_0) = \xi$$

$$\varphi_1(t) = \xi + \int_{t_0}^t f(s, \varphi_0(s)) ds$$

$$\varphi_k(t) = \xi + \int_{t_0}^t f(s, \varphi_{k-1}(s)) ds$$

For small enough $t_B - t_A$ get $\varphi_k \xrightarrow[k \rightarrow \infty]{\text{uniformly in } t} y(t)$

Example $\dot{y} = y, \quad y(0) = \xi$

$$\varphi_0(t) = \xi$$

$$\varphi_1(t) = \xi + \int_0^t \varphi_0(s) ds = \xi + \int_0^t \xi ds = (1+t)\xi$$

$$\varphi_2(t) = \xi + \int_0^t (1+s)\xi ds = \xi + \frac{(1+s)^2 - 1}{2} \xi$$

$$= \xi + \left(t + \frac{t^2}{2}\right)\xi = \xi \left(1 + t + \frac{t^2}{2}\right) = \xi \sum_{k=0}^2 \frac{t^k}{k!}$$

$$\varphi_{k+1}(t) = \xi + \int_0^t \left(1 + \frac{s}{1} + \frac{s^2}{2} + \dots + \frac{s^k}{k!}\right) \xi ds = \xi \left(1 + \frac{t}{1} + \frac{t^2}{2} + \dots + \frac{t^{k+1}}{(k+1)!}\right)$$

$\varphi_k \xrightarrow[k \rightarrow \infty]{} \xi e^t$

Lipschitz property

4

For $\varphi: \mathbb{R}^m \rightarrow \mathbb{R}^n$
is said to possess the Lipschitz property with the Lipschitz constant $L > 0$
if $\forall x_1, x_2 \in \mathbb{R}^m$ (or over the function domain)

$$\|\varphi(x_1) - \varphi(x_2)\| \leq L \|x_1 - x_2\|$$

Recalling, $\|x\|$ is called norm of x

$$\|x\| \geq 0, \quad \|x\| = 0 \Leftrightarrow x = 0$$

$$\|x_1 + x_2\| \leq \|x_1\| + \|x_2\|, \quad \|\lambda x\| = |\lambda| \|x\|$$

(analogous to the absolute value)

$$\Rightarrow \|x_1 + x_2\| \geq \|x_1\| - \|x_2\|$$

Example $\varphi: \mathbb{R} \rightarrow \mathbb{R}$, φ' bounded, continuous
 $|\varphi'(x)| \leq L$

$$\Rightarrow \varphi(x_1) - \varphi(x_2) = \varphi'(\theta)(x_1 - x_2),$$

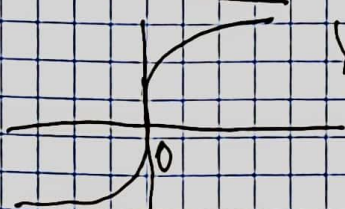
Lagrange: $(x_2 + \theta(x_1 - x_2)), \theta \in (0, 1)$

$$|\varphi(x_1) - \varphi(x_2)| \leq L |x_1 - x_2| \quad \text{QED}$$

\Rightarrow $\cos x$ is a Lipschitz function, $L=1$

Example $\varphi(x) = \sqrt[3]{x}$ is not Lipschitz at 0

$$\varphi'(x) = \frac{1}{3} x^{-\frac{2}{3}}, \quad \lim_{x \rightarrow 0} \varphi'(x) = \infty$$



$$\text{Let } x_2 = 0 \quad \frac{\varphi(x_1) - \varphi(0)}{x_1 - 0} = \frac{x_1^{\frac{1}{3}}}{x_1} = x_1^{-\frac{2}{3}}$$

unbounded

Proposition

5

1. Elementary functions

$\ln x, e^x, \cos x, x^2, x^n$ ($n \in \mathbb{N}$),
their inverse functions are Lipschitzian
over each compact interval (closed segment)
where they are defined.

2. $\varphi_1, \varphi_2: \mathbb{R} \rightarrow \mathbb{R}$ Lipschitzian locally

$\alpha, \beta \in \mathbb{R}$ then

$\alpha \varphi_1 + \beta \varphi_2, \varphi_1 \cdot \varphi_2, \varphi_1^{-1}$ (if $\varphi_1' \neq 0$), $\frac{\varphi_1}{\varphi_2}$ (if $\varphi_2 \neq 0$)

$\varphi_1 \circ \varphi_2$ composition of functions are Lipschitzian

proofs are straight-forward

Example: $\varphi_1 \circ \varphi_2$ $x \xrightarrow{\varphi_2} y \xrightarrow{\varphi_1} z$

$$\frac{d}{dx} \varphi_1(\varphi_2(x)) = \underbrace{\varphi_1'(y)}_{\text{bounded}} \cdot \varphi_2'(x)$$

similarly functions with many arguments are considered

Example: $\cos(x^5 \operatorname{tg}(y) + z)$

is Lipschitzian in x, y, z

for $(x, y, z) \in [-100, 100] \times [-1, 1]$

$x \in [-1000, 2000]$

(Cartesian product)

Lipschitz property with respect to a part of arguments

6

$$\| \varphi(x, y_1) - \varphi(x, y_2) \| \leq L \| y_1 - y_2 \|$$

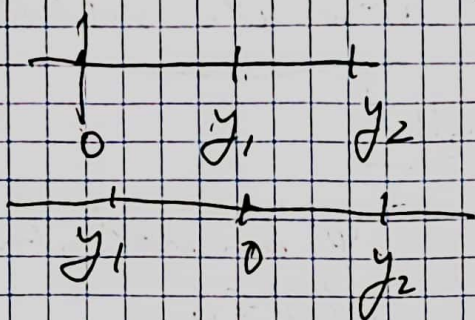
$\forall x, y_1, y_2$

Examples

$|xy| \quad x, y \in [-1, 1]$

$$|xy_1| - |xy_2| = |x| (|y_1| - |y_2|) \leq |x| (|y_1| - |y_2|)$$

$$|y_1| - |y_2| \leq \min(|y_1|, |y_2|) \leq |y_1 - y_2|$$



(cases: $y_1, y_2 > 0, y_1, y_2 < 0$)

$|y|$ - Lipschitz $L=1$

$\varphi(x, y) = (x^2 + 1) \sqrt{|y|}$ non-Lipschitz around $y=0$

$$\frac{(x^2 + 1) \sqrt{|y|} - 0}{|y|} = \frac{x^2 + 1}{\sqrt{|y|}} \text{ unbounded}$$

$x^{\frac{2}{3}} y$ locally Lipschitz in y

$$|x^{\frac{2}{3}} y_1 - x^{\frac{2}{3}} y_2| \leq x^{\frac{2}{3}} |y_1 - y_2|$$

locally bounded

but not Lipschitz in x at $x=0$

$$|x_1^{\frac{2}{3}} y - x_2^{\frac{2}{3}} y| \leq |x_1^{\frac{2}{3}} - x_2^{\frac{2}{3}}| |y| \quad x_2=0 \Rightarrow x_1^{\frac{2}{3}} |y| \text{ unbounded}$$

35 Examples

7

1. $e^{x^2 \cdot \ln y} + \arctan\left(\frac{x}{y-1}\right)$
 is Lipschitz in x for $y \neq 0$ and $y \in [\varepsilon, 1-\varepsilon]$
 is not Lipschitz in y for any x $0 < \varepsilon < \frac{1}{2}$

2. $(1 + \cos x)^{\frac{1}{2}} e^y$ is ^{locally} Lipschitz in y
 for any $x \in \mathbb{R}$
 is not Lipschitz in x in vicinities
 of $-\pi + 2k\pi, k \in \mathbb{Z}$

Final formulation of the $\exists!$ Theorem

$$\left[\begin{array}{l} \dot{y} = f(t, y), \quad y \in \mathbb{R}^n \\ y(t_0) = \xi \quad \text{initial conditions} \end{array} \right] \text{Cauchy problem}$$

① Let f be continuous in t, x .

Then there exists a local solution

$$(\exists \varepsilon > 0: y: [t_0 - \varepsilon, t_0 + \varepsilon] \rightarrow \mathbb{R}^n, \quad y(\cdot) \text{ differentiable})$$

$$\left(\begin{array}{l} \text{and } y(t_0) = \xi, \quad \dot{y}(t) = f(t, y(t)) \\ t \in [t_0 - \varepsilon, t_0 + \varepsilon] \end{array} \right)$$

$$\left[\begin{array}{l} \|\xi\| \leq M \\ |t - t_0| \leq \delta_t \\ \|y - \xi\| \leq \delta_y \end{array} \right]$$

$$\varepsilon = \min\left\{\delta_t, \frac{\delta_y}{M}\right\}$$

2. Under conditions 1. Let

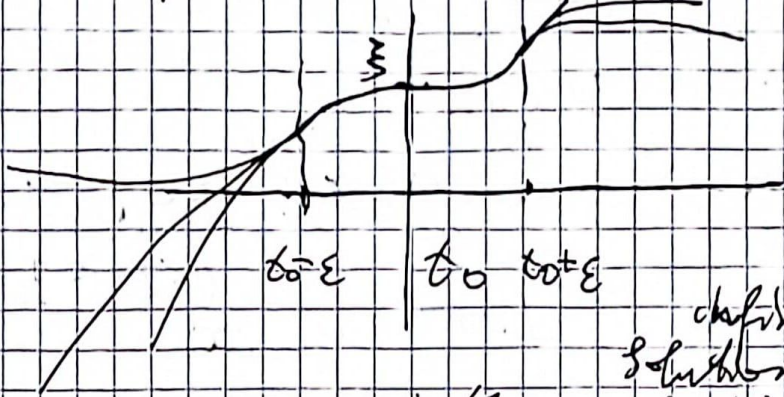
② Let f be not only continuous, but also Lipschitzian in y : $\forall t \|f(t, y_1) - f(t, y_2)\| \leq L \|y_1 - y_2\|$

Then this local solution is unique

$$\text{for } t \in [t_0 - \varepsilon, t_0 + \varepsilon], \quad \varepsilon = \min\left\{\frac{\delta_t}{L}, \delta_t, \frac{\delta_y}{M}\right\}$$

Uniqueness solution meaning!

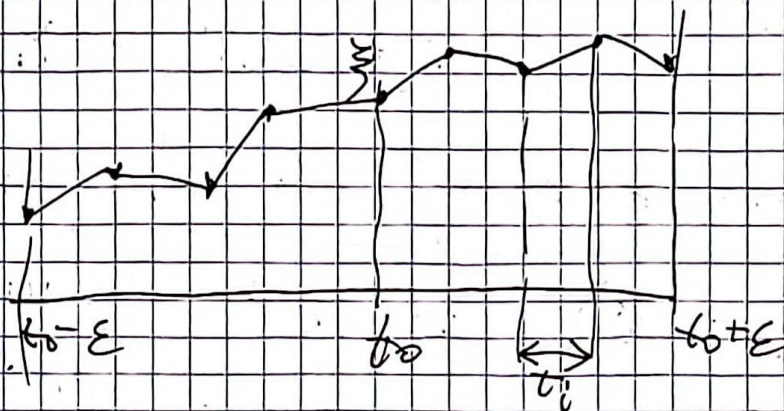
8



There can be infinitely many solutions, but they coincide over $[t_0 - \epsilon, t_0 + \epsilon]$

Idea of the proof!

1. An Euler approximation is constructed



$$y(t_{i+1}) = y(t_i) + f(t_i, y(t_i)) \Delta t_i$$

$$\max \Delta t_i \rightarrow 0$$

No solution can leave the ball



in time $\epsilon < \frac{\rho_0}{M}$

Theorem Arzela-Ascoli

Any infinite sequence $y_k^{(i)}: [t_0 - \epsilon, t_0 + \epsilon] \rightarrow \mathbb{R}^n$

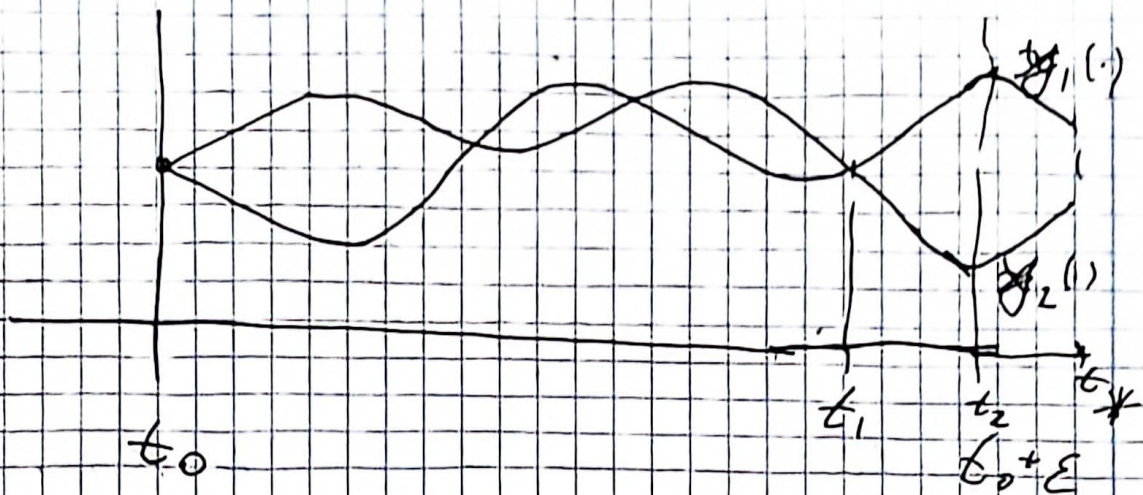
(precompactness property) with bounded $(\|y_k(t)\| \leq \|z\| + \rho_0)$

and Lipschitzian $\|y_k^{(i)}\| \leq \max \|f\| = M$

contains a subsequence uniformly and converging to a Lipschitzian function

A. If f is differentiable B , it satisfies the DS

2. uniqueness:



Assume that there exists $t_* \neq t_0$: $y_1(t_*) \neq y_2(t_*)$

Let $t_* > t_0$, $t_0 < t_* \leq t_0 + \epsilon$

Let $t_1 = \sup \{ t \mid y_1(t) = y_2(t) \}$
 $t \in [t_0, t_*]$

Lemma: 1. $t_1 < t_*$. Indeed $y_1(t_*) \neq y_2(t_*)$
 \Rightarrow also in a vicinity

2. $\forall t \in [t_1, t_*] : y_1(t) \neq y_2(t)$
 otherwise $t_1 \neq \sup$

Define $t_2 = \arg \max_{t \in [t_1, t_*]} \|y_1(t) - y_2(t)\|$.

$$\|y_1(t_2) - y_2(t_2)\| = \max_{t \in [t_1, t_*]} \|y_1(t) - y_2(t)\| = M_y$$

$$\begin{aligned} \text{Then } M_y &= \|y_1(t_2) - y_2(t_2)\| = \left\| \int_{t_1}^{t_2} \dot{y}_1(s) ds - \int_{t_1}^{t_2} \dot{y}_2(s) ds \right\| \\ &= \left\| y_1(t_1) + \int_{t_1}^{t_2} \dot{y}_1(s) ds - y_2(t_1) - \int_{t_1}^{t_2} \dot{y}_2(s) ds \right\| \\ &= \left\| \int_{t_1}^{t_2} [f(t, y_1(s)) - f(t, y_2(s))] ds \right\| \end{aligned}$$

$$\leq \left\| \int_{t_1}^{t_2} L \|y_1(s) - y_2(s)\| ds \right\| \leq \left\| \int_{t_1}^{t_2} L M_y ds \right\|$$

$$\leq |t_2 - t_1| L M_y \leq |t_* - t_1| L M_y \leq (t_* - t_0) L M_y$$

Thus $1 \leq \frac{\Delta t(t_* - t_0)}{L}$

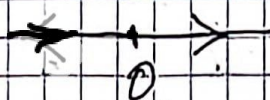
10

Now choose t_* sufficiently close to t_0 so that it will be a contradiction
QED

Counter example!

The requirement is important

$$\dot{y} = 3y^{\frac{2}{3}}$$



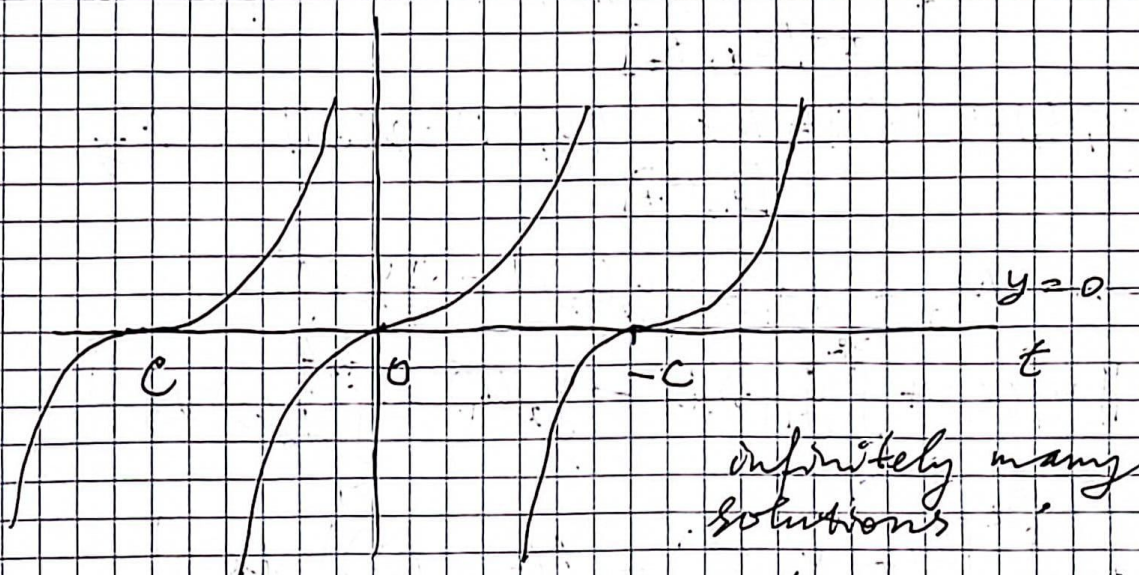
$y = 0$ is a solution

The Lipschitz property holds everywhere except $y = 0$

$$y \neq 0 \Rightarrow \frac{1}{3} y^{-\frac{2}{3}} \dot{y} = 1$$

$$y^{\frac{1}{3}} = \int \frac{1}{3} y^{-\frac{2}{3}} \dot{y} dt = t + C$$

$$y = (t + C)^3, \quad C \in \mathbb{R}, \quad y = 0$$



At any moment $t = -C, C \in \mathbb{R}$ the solution can come from below or leave to above, or stay at 0

$$y = \begin{cases} (t + C_2)^3 & t > -C_2 \\ 0 & t \in [-C_1, -C_2] \\ (t + C_1)^3 & t \leq -C_1 \end{cases}$$

The proof of the $\exists!$ theorem
 in the book by Arnold is based
 on the Picard approximation
 and the principle of the unique
 fixed point of a contraction mapping.
We omit it here

11

Theorem (Arnold) $\dot{y} = f(t, y)$
 $y(t_0) = \xi \Rightarrow y = Y(t, \xi)$

If $f \in C^k$ on (t, y) (in both!)

then $\forall \epsilon > 0$ $\exists \delta > 0$ $\exists \eta > 0$ $\exists \tau > 0$
 (Depends on ϵ, η, τ and initial conditions!)

Dependence on parameters:

$\dot{y} = f(t, y, \alpha)$ $y \in \mathbb{R}^n, t \in [t_0, t_0 + \tau]$
 $f \in C^k$ $\forall \alpha \in \mathbb{R}^m$

$\Leftrightarrow (\dot{y} = f(t, y, \alpha), y(t_0) = \xi)$
 $\Leftrightarrow (\dot{y} = f(t, y, \alpha), y(t_0) = \xi, \alpha = \alpha_0)$
 (initial conditions)

$\Rightarrow y = Y(t, \xi, \alpha) \in C^k$

Continuous dependence on α
 right-hand side

Theorem $\dot{y} = f(t, y) + \epsilon w(t, y)$ $f, w \in C$
 $\max_{\partial \epsilon} y_\epsilon(t_0) = \xi$

$\lim_{\epsilon \rightarrow 0} y_\epsilon(t, \xi) = y_0(t, \xi)$ uniformly on $t \in [t_0, t_0 + \tau]$